

FIG.1

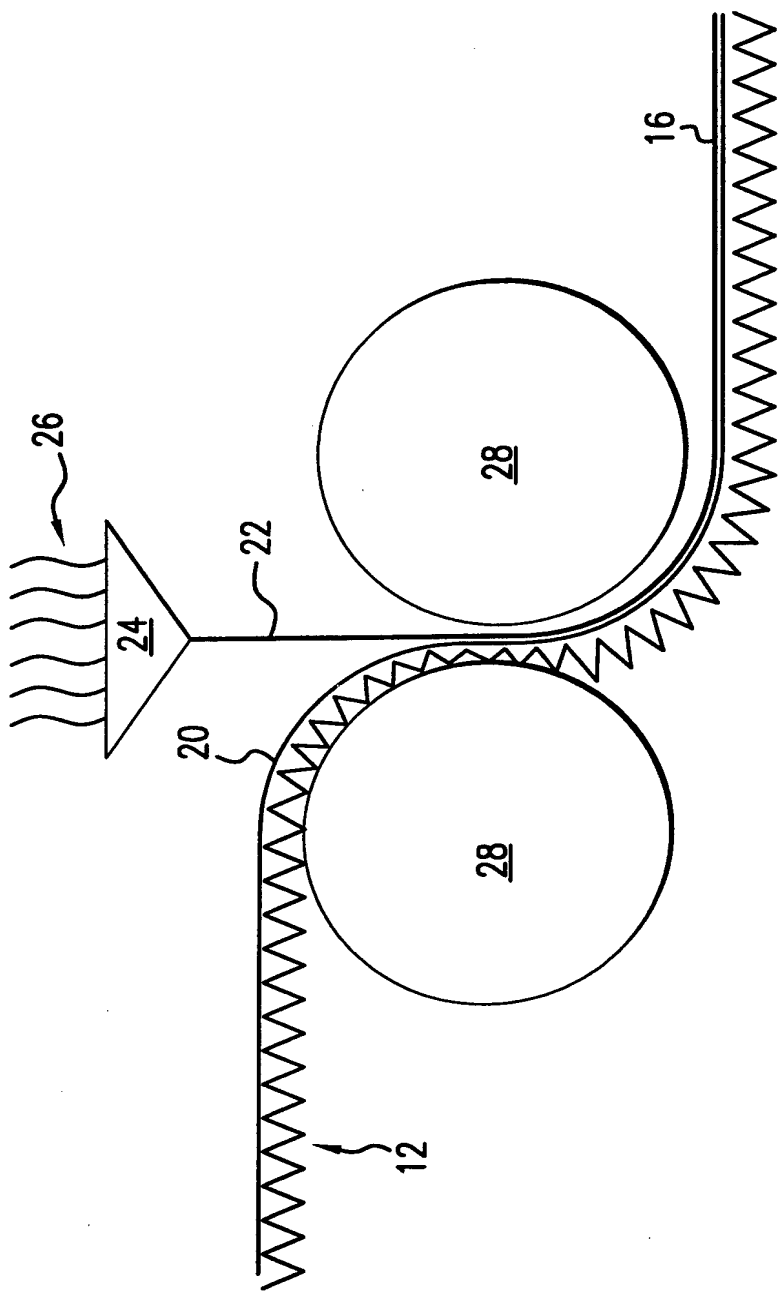


FIG.2

FIG. 3 is a schematic diagram of a mechanical system. The system includes a horizontal member 12, a vertical member 16, and a diagonal member 20. A first circular component 30 is connected to the horizontal member 12 at one end and the diagonal member 20 at the other. A second circular component 32 is connected to the vertical member 16 at one end and the diagonal member 20 at the other. A third circular component 32 is connected to the horizontal member 12 at one end and the diagonal member 20 at the other. The horizontal member 12 is shown with a wavy line indicating a spring or a flexible joint. The vertical member 16 is shown with a wavy line indicating a spring or a flexible joint. The diagonal member 20 is shown with a wavy line indicating a spring or a flexible joint.

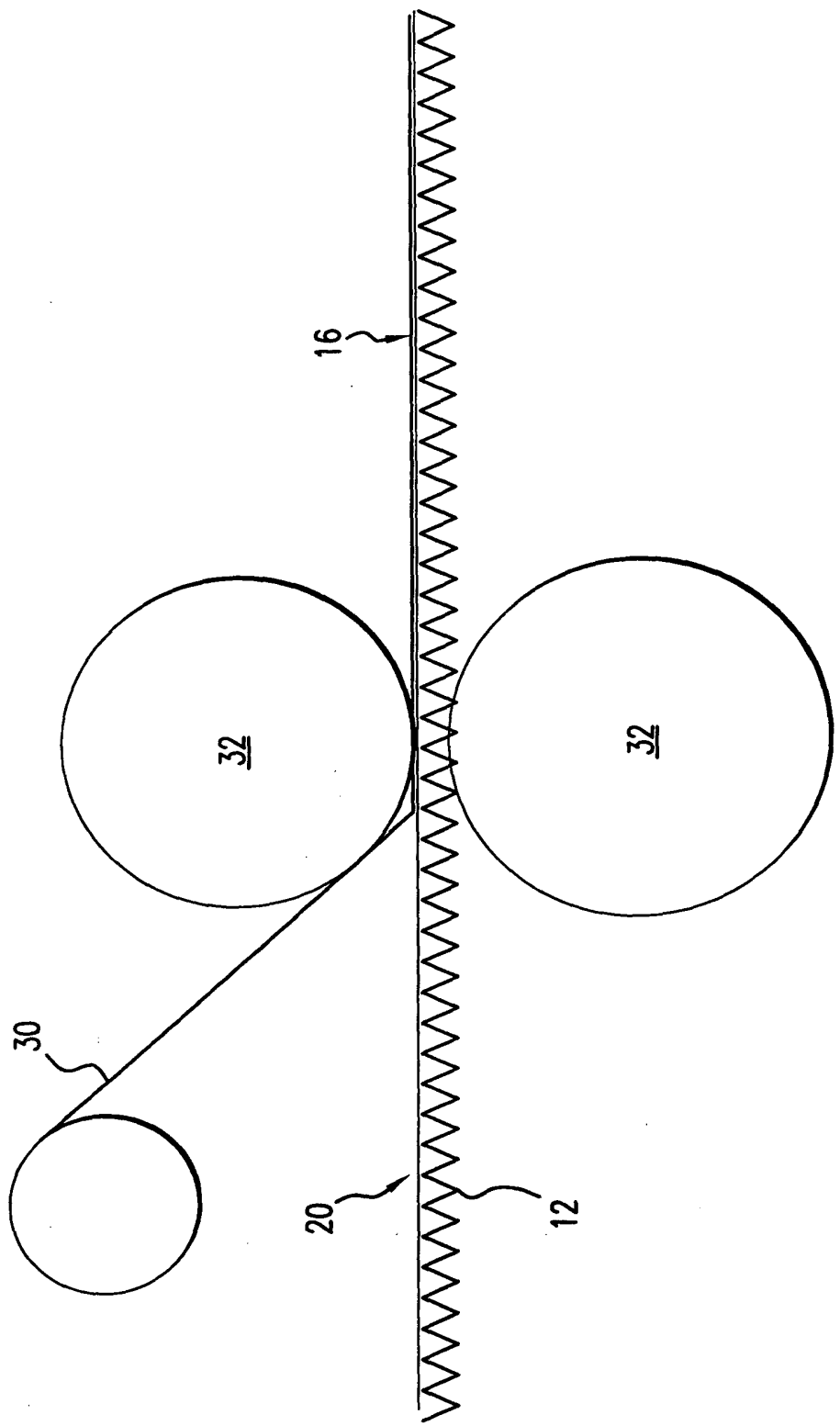


FIG.3